Improving the Operating System with Reconfigurable Hardware
(FGBS’11)

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Challenges in Operating Systems

Is there a way to tackle challenging properties of operating systems:

- **Security**: Running software must not alter security policies

- **Safety**: Entering a safe state, even when the system crashes

- **Determinism**: Enforcing hard limits to reach real-time goals

- **Performance**: Increasing system throughput
Today, cheap reconfigurable hardware is readily available
- Big low-cost FPGAs are common

Reconfigurable hardware makes building adaptable hardware possible
- Logic cells contain boolean lookup tables which can be reprogrammed
- Flip-flops and RAM cells can be used for data storage
- This makes it feasible to adapt hardware to the requirements of software
State of the FPGA

Today FPGAs are mainly used in userspace applications
- Applications: Video filtering, Signal pre-/postprocessing, SDR, ...
- OS: cryptographic operations, manage FPGA resources for the user

Reconfigurable hardware is designed independently from software
- Static interfaces between hard- and software
- Interface changes need to be made in both “worlds”

As software is “easier” to develop, software usually follows hardware
- Software becomes more complex to keep hardware simple

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Integrating FPGAs into commodity systems

- FPGAs are easily integrated into modern systems
  - **PCI**: Full PCI bridges can be synthesized into (cheap) low-end FPGAs
  - **PCIe**: Current FPGAs have integrated PCIe endpoints

- Processor manufacturers even add FPGAs to new processors
Integrating FPGAs into commodity systems

- FPGAs are easily integrated into modern systems
  - *PCI*: Full PCI bridges can be synthesized into (cheap) low-end FPGAs
  - *PCle*: Current FPGAs have integrated PCle endpoints

- Processor manufacturers even add FPGAs to new processors

FPGAs are broadly available
Reconfigurable hardware should be used by the operating system!
Outline

Motivation

Problem

  Interfacing an FPGA with the OS
  Accessing and Understanding OS Data
  Coping with Operating System Changes

Framework

  Automatic Interface Generation
  DMA Abstraction
  Hardware OS Component Implementation

Evaluation

  Malicious-Process Killer
  Simple Hardware Scheduler

WIP and Conclusion

  Generating Hardware from OS code
Interfacing an FPGA with the OS

- To achieve good performance, the hardware needs to access data without asking the OS for it
- PCI and PCIe both provide DMA capabilities
  - Usually used with OS-supplied DMA memory regions
  - But accessing the whole physical memory is possible
  - The operating system is not involved at all
  ⇒ Ideal interface for high-performance reconfigurable hardware
## Accessing and Understanding OS Data

- Data accessible by DMA is only meaningful to the kernel.

```
c14d75a0: c9ba 1fab 9d1c 622e 9735 ea5e 4c57 b730
c14d75b0: dc6c 3afe d38f 61a4 81fd 6eb6 b18e e8c6
c14d75c0: 1043 ce08 8232 2ab9 2529 1510 5f49 539f
c14d75d0: b5e5 ddb7 b378 bd88 3981 db6f 06bd d361
```

- But the OS should not be bothered to convert interesting bits of data.

- Hardware design needs to know operating system data formats.
  - Operating system structures have to be described in hardware.
  - Member offsets in structures can be hard-wired into the implementation.

<table>
<thead>
<tr>
<th>Field</th>
<th>Offset</th>
<th>Size</th>
</tr>
</thead>
<tbody>
<tr>
<td>state</td>
<td>0</td>
<td>7</td>
</tr>
<tr>
<td>usage</td>
<td>8</td>
<td>8</td>
</tr>
<tr>
<td>ptrace</td>
<td>16</td>
<td>8</td>
</tr>
<tr>
<td>flags</td>
<td>24</td>
<td>8</td>
</tr>
<tr>
<td>lock_depth</td>
<td>32</td>
<td>8</td>
</tr>
</tbody>
</table>

⇒ Hardware is able to access and understand OS data.
Coping with Operating System Changes

- Operating system internals change with every version
- Best example: Linux
  - No stable kernel API
  - Memory layout even dependent on kernel configuration
- Transforming system state to a hardware-defined format is expensive
- Manually adapting hardware to changing software is fragile

Solution
Generate hardware interfaces automatically

Linux 2.6.37
HW scheduler
Linux 2.6.38
HW scheduler
(see linux-2.6/Documentation/stable_api_nonsense.txt)
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A Framework for Hardware OS Components

**Mechanisms**
- Automatic interface generation
- Partial hardware component generation from kernel source code
- Integration into kernel build process

**Features**
- Abstraction of DMA transfers
- Two-way notifications between soft- and hardware

Mechanisms

```
sched.c  gcc  sched.o  dwarf2vhdl
roccstubgen  sched.vhdl  dma.vhdl  int.vhdl
xst  sched-if.vhdl
sched.bit
```

Features

```
OS
CPU
FPGA
PCI
RAM
```

Two-way notifications

read/write

DMA

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Improving the OS with Reconfigurable Hardware

Framework
Automatic Interface Generation

- Use DWARF debug symbols in kernel objects to generate interfaces
- Memory layout as created by the compiler
- Used for VHDL interface generation
- Stable interface for hardware implementation
- Integrates in kernel build process

```vhdl
entity struct_simple is port ( 
  signal flags_i: in std_logic;
  signal info_i: in std_logic;
  signal data_i: in std_logic;
  signal base_addr_i: in std_logic_vector(31 downto 0);
  signal addr_o: out std_logic_vector(31 downto 0);
  signal clk_i: in std_logic);
end entity struct_simple;
architecture struct_simple__arch of struct_simple is
begin
  process (clk_i)
  begin
    if (clk_i'event and clk_i = '1') then
      if (flags_i = '1') then
        addr_o <= base_addr_i + 0 + 0;
      elsif (info_i = '1') then
        addr_o <= base_addr_i + 0 + 2;
      elsif (data_i = '1') then
        addr_o <= base_addr_i + 0 + 4;
      else
        object file
      end if;
    end process (clk_i);
  end process (clk_i);
end architecture struct_simple__arch;
```
Automatic Interface Generation (2)

1. Reads an object file generated with DWARF debugging symbols
2. Determines data type, location, size and name for each Debugging Information Entry (DIE)
3. Generates VHDL entities for each structure
4. Generates VHDL accessor code for each member of a structure
5. Connects each VHDL entity to the DMA multiplex of the framework

```vhdl
architecture struct_simple_arch of struct_simple is
begin
process (clk_i)
begin
if (clk_i 'event and clk_i = '1') then
  if (flags_i = '1') then
    addr_o <= base_addr_i + 0 + 0;
  elsif (info_i = '1') then
    addr_o <= base_addr_i + 0 + 2;
  elsif (data_i = '1') then
    addr_o <= base_addr_i + 0 + 4;
  else
    addr_o <= base_addr_i;
  end if;
end if;
end process;
end architecture struct_simple_arch;
```

```c
struct struct_simple {
  unsigned short flags;
  char info[2];
  char *data;
};
```
DMA Abstraction

- DMA transfers are handled by the framework
  - Hardware component accesses data with simple reads and write
  - All timing critical operations are handled by the framework

- Multiple components can be active at the same time

- Framework will also provide handling of coordination between operating system and hardware
  - No atomic read-modify-write possible
  - But shared data-structures have to be consistent

- Hardware components can be (de-)activated on-the-fly
Hardware OS Component Implementation

- Components are currently manually implemented in VHDL
- Only core functionality needs to be implemented
- Two-way notifications are provided by the framework
  - Notification of the OS by interrupts is provided
  - Notification of the hardware by the OS is provided
- Visible and invisible components possible
  - **Visible**: The operating system knows and interacts with the component
  - **Invisible**: The component works independently from the operating system
Building Hardware OS Components

- sched.c → gcc → sched.o
- sched-if.vhdl
- sched.vhdl
- dma.vhdl
- int.vhdl
- xst → sched-if.vhdl
- rocccstubgen
- sched.vhdl
- dma.vhdl
- int.vhdl
- xst
- sched.bit
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WIP and Conclusion
Generating Hardware from OS code
Two hardware OS components were built using the framework
- Malicious-process killer (invisible component)
- Simple scheduler (visible component)

Hardware is synthesized for a XILINX Spartan 3 (XC3S1500) FPGA

FPGA is connected to the PCI bus of the host system

Host system is an Intel Pentium 4 with 2.4GHz

Operating system on the host is Linux 2.6.32
Malicious-Process Killer

- Component terminates unwanted processes
  - Constantly iterates over the task structure
  - Executable name is compared to a blacklist
    - Process identification could also be more complex (e.g. memory checksums)
  - If the name is on the list, a KILL signal is added to the pending signals of the process

- The operating system does not know the hardware component exists
  - It cannot be disabled or modified during run-time
  - Rebooting the system will not disable the hardware
  - A remote attacker has no way to disable the component
Simple Hardware Scheduler

- Simple uniprocessor round-robin scheduler
- Replaces `pick_next_task()` in `linux/kernel/sched.c`
- Works on the global process list `task_struct`
- Determines next process by iterating through list
- Writes the address of the next `task_struct` to be scheduled to a memory location
- Sends an interrupt after the allotted time slice for the process is reached
- Can be activated and de-activated at run-time
Access to the Process List

- `task_struct` is converted by `dwarf2vhdl`
- Complex structure with multiple embedded sub-structures
- 127 members in Linux 2.6.32

- Kernel linked list is traversed in hardware
- Conversion between virtual and physical addresses is done in hardware
- Address of first element (`init_task`) is determined during kernel compile-time, can be changed at run-time
Preliminary Results

- Scheduling jitter is only affected by variance in soft interrupt latency
  - | Best | Worst | Average |
  - | 6.3µs | 13.8µs | 7.8µs |
  - (1000 measurements of soft interrupt latency on the host)

- These latencies also occur with the software-based scheduler (timer)

- Only small changes to existing kernel code necessary (≈ 10 lines)

- Decision process is independent from operating system

- Determining the next process only involves reading one memory location

- Task switching is initiated as soon as the OS receives the interrupt
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WIP: Generating Hardware from OS code

- Is it possible to translate an operating system component into hardware?
  - **SystemC** is suitable for writing hardware in C++, not for translating existing software into hardware, FPGA compilers are expensive and closed.
  - The open-source **Riverside Optimizing Compiler for Configurable Computing (ROCCC)**\(^2\) can only translate simple C sources to VHDL.

- Work based on **ROCCC**, as it is available and extendable.
  - Automatically simplify operating system code for ROCCC.
  - Simplified code is used to generate a base VHDL component.
  - Final component is built by manually extending the base component.

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\(^2\) Guo, Buyukkurt, Najjar, Vissers: Optimized Generation of Data-path from C Codes for FPGAs, DATE 2005
Conclusion

- Framework for hardware operating system components
  - Interface generation
  - Memory access abstraction
  - Hardware OS components for Linux
    - Simple scheduler
    - Malicious-process killer

⇒ Reconfigurable hardware should be used by the operating system

Future work

- Base hardware component generation using ROCCC
- Implementation of more hardware OS components
  - **Security**: Hardware-based policy enforcement
  - **Determinism**: Real-time scheduling
  - **Performance**: Network routing